

# A Homogeneous Model for Mixed Complementarity Problems over Symmetric Cones

申請中 筑波大学 \* 林ヨウ (火偏に華) 東 LIN Yedong

01703540 筑波大学 吉瀬章子 YOSHISE Akiko

## 1 Introduction

In this article, we propose a homogeneous model for mixed complementarity problems (MCPs) over symmetric cones, and discuss its theoretical aspects. The model is a natural extension of the model in [1] for monotone complementarity problems over the non-negative orthant in  $\mathfrak{R}^n$ . The analyses are based on [4] where the weighted paths for nonlinear monotone MCPs are studied. We show the existence of a path having the following properties: (a) The path is bounded and has a trivial starting point without any regularity assumption concerning the existence of feasible or strictly feasible solutions. (b) Any accumulation point of the path is a solution of the homogeneous model. (c) If the original problem is solvable, then every accumulation point of the path gives us a finite solution. (d) If the original problem is strongly infeasible, then every accumulation point of the path gives us a finite certificate proving infeasibility.

## 2 MCPs over symmetric cones

Let  $V$  be an  $n$ -dimensional real vector space and  $(V, \gamma)$  be a Euclidian Jordan algebra with an identity element  $e$ . We denote by  $K$  a symmetric cone of  $V$  which is a self-dual closed convex cone. It is known that a cone in  $V$  is symmetric if and only if it is the cone of squares of  $V$  given by  $K = \{x \circ x : x \in V\}$  (cf. [2]).

The MCP over the symmetric cone is given by

$$\begin{aligned} & \text{Find } (x, y, z) \in K \times K \times \mathfrak{R}^m, \\ & \text{s.t. } F(x, y, z) = 0, x \circ y = 0. \end{aligned} \quad (1)$$

where  $F$  is a continuously differentiable function from  $K \times K \times \mathfrak{R}^m$  to  $V \times \mathfrak{R}^m$ .

Observe the following nonlinear semidefinite program:

$$\text{Min } \theta(x) \text{ s.t. } G(x) \in -S_+^n, h(x) = 0 \quad (2)$$

where  $S_+^n$  is the cone of semidefinite matrices in the set  $S^n$  of  $n \times n$  symmetric matrices,  $\theta : \mathfrak{R}^m \rightarrow \mathfrak{R}$ ,  $G : \mathfrak{R}^m \rightarrow S^n$  and  $h : \mathfrak{R}^m \rightarrow \mathfrak{R}^p$  are given smooth mappings. It has been shown that an optimality condition for (2) can be formulated as a problem of the form (1) under an appropriate constraint qualification[3].

We say that an MCP is

- (asymptotically) feasible iff there exists a bounded sequence  $\{x^{(k)}, y^{(k)}, z^{(k)}\} \subseteq \text{int}K \times \text{int}K \times \mathfrak{R}^m$  such that  $\lim_{k \rightarrow \infty} F(x^{(k)}, y^{(k)}, z^{(k)}) = 0$ ,
- strongly infeasible iff  $0 \notin \text{cl}(F(K \times K \times \mathfrak{R}^m))$ .

We use the following assumption on the map  $F$ .

**Assumption 2.1 (i)**  $F$  is  $(x, y)$ -equilevel-monotone on its domain, i.e., for every  $(x, y, z)$  and  $(x', y', z')$  in the domain of  $F$  satisfying  $F(x, y, z) = F(x', y', z')$ ,  $\langle x - x', y - y' \rangle \geq 0$  holds.

(ii)  $F$  is  $z$ -bounded on its domain, i.e., for every  $\{(x^{(k)}, y^{(k)}, z^{(k)})\}$  in the domain of  $F$ , if  $\{(x^{(k)}, y^{(k)})\}$  and  $\{F(x^{(k)}, y^{(k)}, z^{(k)})\}$  are bounded then the sequence  $\{z^{(k)}\}$  is also bounded.

(iii)  $F(x, y, z)$  is  $z$ -injective on its domain, i.e., if  $(x, y, z)$  and  $(x, y, z')$  lie in the domain of  $F$  and satisfy  $F(x, y, z) = F(x, y, z')$  then  $z = z'$ .

## 3 A homogeneous model

In this section, we give a homogenous model for solving MCPs where the map  $F : K \times K \times \mathfrak{R}^m \rightarrow V \times \mathfrak{R}^m$  is of the form

$$F(x, y, z) = (y - \psi_1(x, z), \psi_2(x, z))$$

and  $\psi := (\psi_1, \psi_2) : K \times \mathfrak{R}^m \rightarrow V \times \mathfrak{R}^m$ . For the problem, we consider the following homogeneous model(HMCP):

$$\begin{aligned} & \text{Find } (x, \tau, y, \kappa, z) \in (K \times \mathfrak{R}_{++}) \times (K \times \mathfrak{R}_+) \times \mathfrak{R}^m, \\ & \text{s.t. } F_H(x, \tau, y, \kappa, z) = 0, (x, \tau) \circ_H (y, \kappa) = 0 \end{aligned}$$

where  $F_H : (K \times \mathfrak{R}_{++}) \times (K \times \mathfrak{R}_+) \times \mathfrak{R}^m \rightarrow (V \times \mathfrak{R}) \times \mathfrak{R}^m$  and  $(x, \tau) \circ_H (y, \kappa)$  are given by

$$F_H(x, \tau, y, \kappa, z) := \begin{pmatrix} y - \tau \psi_1(x/\tau, z/\tau) \\ \kappa + \langle \psi_1(x/\tau, z/\tau), x \rangle + \psi_2(x/\tau, z/\tau)^T z \\ \tau \psi_2(x/\tau, z/\tau) \end{pmatrix}$$

and

$$(x, \tau) \circ (y, \kappa) := \begin{pmatrix} x \circ y \\ \tau \kappa \end{pmatrix}.$$

We also define the scalar product  $\langle (x, \tau), (y, \kappa) \rangle_{\mathbb{H}}$  by

$$\langle (x, \tau), (y, \kappa) \rangle_{\mathbb{H}} := \langle x, y \rangle + \tau \kappa.$$

For ease of notation, we use the following symbols:  $V_{\mathbb{H}} := V \times \mathbb{R}$ ,  $K_{\mathbb{H}} := K \times \mathbb{R}_+$ ,  $x_{\mathbb{H}} := (x, \tau) \in V_{\mathbb{H}}$ ,  $y_{\mathbb{H}} := (y, \kappa) \in V_{\mathbb{H}}$ , and define  $\psi_{\mathbb{H}} := (\psi_{\mathbb{H}1}, \psi_{\mathbb{H}2})$  by

$$\begin{aligned} \psi_{\mathbb{H}1}(x_{\mathbb{H}}, z) &:= \\ &\begin{pmatrix} \tau \psi_1(x/\tau, z/\tau) \\ -\langle \psi_1(x/\tau, z/\tau), x \rangle - \psi_2(x/\tau, z/\tau)^T z \end{pmatrix}, \\ \psi_{\mathbb{H}2}(x_{\mathbb{H}}, z) &:= \tau \psi_2(x/\tau, z/\tau). \end{aligned}$$

We can easily see that  $\text{int}K_{\mathbb{H}} = \text{int}K_{\mathbb{H}} \times \mathbb{R}_{++}$  and

$$F_{\mathbb{H}}(x_{\mathbb{H}}, y_{\mathbb{H}}, z) = \begin{pmatrix} y_{\mathbb{H}} - \psi_{\mathbb{H}1}(x_{\mathbb{H}}, z) \\ \psi_{\mathbb{H}2}(x_{\mathbb{H}}, z) \end{pmatrix}.$$

Note that since  $K_{\mathbb{H}} = \{x_{\mathbb{H}}^2 = (x^2, \tau^2) : x_{\mathbb{H}} \in V_{\mathbb{H}}\}$ , the closed convex cone  $K_{\mathbb{H}}$  is the symmetric cone of  $V_{\mathbb{H}}$ .

## 4 Main results

The following theorems are the main results.

**Theorem 4.1** *Suppose that  $\psi_{\mathbb{H}}$  satisfies Assumption 2.1.*

- (i) *The HMCP is asymptotically feasible and solvable.*
- (ii) *The MCP has a solution if and only if the HMCP has an asymptotical solution  $(x_{\mathbb{H}}^*, y_{\mathbb{H}}^*, z^*) = (x^*, \tau^*, y^*, \kappa^*, z^*)$  with  $\tau^* > 0$ . In this case,  $(x^*/\tau^*, y^*/\tau^*, z^*/\tau^*)$  is a solution of (CP).*
- (iii) *The MCP is strongly infeasible if and only if the HMCP has an asymptotical solution  $(x^*, \tau^*, y^*, \kappa^*, z^*)$  with  $\kappa^* > 0$ .*

**Theorem 4.2** *Suppose that  $\psi_{\mathbb{H}}$  satisfies Assumption 2.1.*

- (i) *The set*

$$\begin{aligned} P &:= \{(x_{\mathbb{H}}(t), y_{\mathbb{H}}(t), z(t)) : \\ &x_{\mathbb{H}} \circ_{\mathbb{H}} y_{\mathbb{H}} = te, \\ &F(x_{\mathbb{H}}, y_{\mathbb{H}}, z) = tF(e, e, 0), \quad t \in (0, 1]\} \end{aligned}$$

*forms a bounded path  $\in \text{int}K_{\mathbb{H}} \times \text{int}K_{\mathbb{H}} \times \mathbb{R}^m$ . Any accumulation point of the path  $P$  is an asymptotically complementary solution of (HMCP).*

- (ii) *If the HMCP has an asymptotically complementarity solution  $(x_{\mathbb{H}}^*, y_{\mathbb{H}}^*, z^*) = (x^*, \tau^*, y^*, \kappa^*, z^*)$  with  $\tau^* > 0$  ( $\kappa^* > 0$ ), the any accumulation point  $(x_{\mathbb{H}}(0), y_{\mathbb{H}}(0), z(0)) = (x(0), \tau(0), y(0), \kappa(0), z(0))$  of the bounded path  $P$  satisfies  $\tau(0) > 0$  ( $\kappa(0) > 0$ ).*

The above two theorems imply that if we have an accumulation point of the central path  $P$ , we can find that the original MCP falls into exactly one of the three categories in Table 1.

$\tau^*/\kappa^*$	= 0	> 0
= 0	other cases	strongly infeasible
> 0	solvable	N/A

Note that the assumption in the theorems is slightly ambiguous since it is concerned with the homogeneous map  $\psi_{\mathbb{H}}$ , but not with the map  $\psi$  appearing in the original MCP. The following proposition gives a class of  $\psi$ s for which  $\psi_{\mathbb{H}}$  satisfies Assumption 2.1.

**Proposition 4.3 (i)** *The map  $\psi_{\mathbb{H}}$  is monotone on  $\text{int}K_{\mathbb{H}} \times \mathbb{R}^m$  whenever  $\psi$  is monotone on  $K \times \mathbb{R}^m$ .*

(ii) *The map  $F_{\mathbb{H}}$  is  $(x_{\mathbb{H}}, y_{\mathbb{H}})$ -everywhere-monotone on  $\text{int}K_{\mathbb{H}} \times \text{int}K_{\mathbb{H}} \times \mathbb{R}^m$  whenever  $\psi$  is monotone on  $K \times \mathbb{R}^m$ .*

(iii) *The map  $F_{\mathbb{H}}$  is  $z$ -bounded on  $\text{int}K_{\mathbb{H}} \times \text{int}K_{\mathbb{H}} \times \mathbb{R}^m$  whenever  $\psi$  is affine and  $z$ -bounded on  $K \times \mathbb{R}^m$ .*

(iv) *The map  $F_{\mathbb{H}}$  is  $z$ -injective on  $\text{int}K_{\mathbb{H}} \times \text{int}K_{\mathbb{H}} \times \mathbb{R}^m$  whenever  $\psi$  is  $z$ -injective on  $K \times \mathbb{R}^m$ .*

## References

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