A ROBUST ENSEMBLE LEARNING USING ZERO-ONE LOSS FUNCTION

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Abstract Classifier is used for pattern recognition in various fields including data mining. Boosting is an ensemble learning method to boost (enhance) an accuracy of single classifier. We propose a new, robust boosting method by using a zero-one step function as a loss function. In deriving the method, the MarginBoost technique is blended with the stochastic gradient approximation algorithm, called Stochastic Noise Reaction (SNR). Based on intensive numerical experiments, we show that the proposed method is actually better than AdaBoost on test error rates in the case of noisy, mislabeled situation.

Keywords: Data Analysis, Data mining, AdaBoost, Zero-one Loss Function, Stochastic Noise Reaction

1. Introduction

Recently, there has been a growing interest in ensemble learning methods that can produce more accurate and better performing models for pattern classification. Ensemble learning method, also known as committee method, refers to a collection of models that learn a target function asymptotically by training a number of individual (base) learners and combining their predictions. It is a technique for dynamic integration of classifiers and, for example, a set of classifiers (e.g., neural networks, RBF networks, etc.) with different weights applied to the same training dataset are known to generate ensembles that are often more accurate than a single classifier. The most widely used and studied ensemble method is called Boosting, proposed by Schapire [16]. The application of Boosting usually improves the prediction quality and leads to improved generalization capabilities, e.g., [1], [3], [4]. Boosting has been very successful and popular in recent years and received great praise in the machine learning, computer science, and statistics communities. For this contribution, the inventors Schapire and Freund received the prestigious ACM Goedel prize in 2003.

Commonly used adaptive version of Boosting is known as the AdaBoost algorithm [4]. The basic idea of AdaBoost is to create a sequence of models by calling a given learning algorithm iteratively, where each model is trained on a re-weighted version of the original dataset. During the training process, the weights associated with misclassified patterns are increased so that, in the next iteration, the base learner is forced to focus on harder patterns to learn. Then, in the subsequent application, the classifications of this ensemble are combined together to form the final prediction. AdaBoost is particularly aggressive in maximizing the smallest margin of samples. The margin can be understood as a measure of difficulty of classification. On binary case, the margin denotes the difference between weighted votes received by the correct label and the misclassified incorrect label of the training example. However, the bigger margin of AdaBoost is achieved at the expense of suffering significant reductions in the margins of those that already have large margins in
the previous training step. So it is noise sensitive and maximization of the smallest margin in the case of noisy data may lead to bad results.

Much has been written about the success of AdaBoost in producing accurate classifiers and it is believed to be resistant against overfitting. Interestingly, however, recent studies with highly noisy patterns, e.g., [7], [13], [14], depict that it is clearly a myth that AdaBoost does not overfit since AdaBoost asymptotically concentrates on the patterns which are hardest to learn. To cope with this problem, some regularized Boosting algorithms [10], [14] are proposed. In this paper, robustness is defined as not to overfit, i.e., to prevent too complicated model from failing to recognize (predict) unknown data. Robustness is measured through the test error rate of model when the model is trained by data containing mislabeled data.

The original AdaBoost is intended for classifiers with zero-one loss function for low noise cases. In the present study, we use the same zero-one loss function, but we target a direct evaluation of its gradient to derive a new robust Boosting algorithm against noisy patterns. Note that this paper is a companion paper to the previous paper of the present authors [15], with different implementations based on MarginBoost algorithm [11].

In the next section, we recapitulate the principles of MarginBoost. Then, in Section 3, we present the zero-one loss function and the gradient approximation technique referred to as Stochastic Noise Reaction (SNR). In Section 4, we propose the new robust boosting method. Results of intensive numerical experiments are presented in Section 5 where we detail cases with noisy, mislabeled patterns. Section 6 contains some concluding remarks.

2. MarginBoost

We assume that the training dataset \((x, y)\) is randomly generated according to some unknown probability distribution \(D\) on \(X \times Y\) where \(X\) is the space of measurements (typically \(X \subseteq \mathbb{R}^n\)) and \(Y\) is the space of labels (\(Y\) is usually a discrete set \(\{\pm 1\}\) or some subset of \(\mathbb{R}\)). The output of classification is denoted as \(\operatorname{sign}(F(x))\), where \(F(x)\) is given by

\[
F(x) = \sum_{t=1}^{T} \beta_t f_t(x),
\]

and \(f_t : X \rightarrow \{\pm 1\}\) are base classifiers from some fixed class \(\mathcal{F}\) (e.g., class of base hypotheses), and \(\beta_t \in \mathbb{R}\) denotes the weights and \(T\) denotes the number of boosting iteration.

The margin of the training data \((x, y)\) with respect to the classifier is defined as \(z = yF(x)\). It is noted that if \(y \neq \operatorname{sign}(F(x))\) then \(yF(x) < 0\), and if \(y = \operatorname{sign}(F(x))\) then \(yF(x) \geq 0\). The margin can be understood as a measure of difficulty of classification. As data has a larger (positive) margin, the example is easier to be classified. On the contrary, as it has a smaller (negative) margin, the data is harder to be classified.

Given a set \(S = \{(x_1, y_1), \ldots, (x_n, y_n)\}\) of \(n\) labeled data pairs generated according to \(D\), we wish to construct a classification model described by Equation (1) so that the probability of incorrect classification \(P_D(\operatorname{sign}(F(x)) \neq y)\) is small. Since \(D\) is unknown and we are only given a training set \(S\), we take the approach of finding the classification model which minimizes the sample risk of some cost function of the margin. That is, for a training set \(S\) we want to find \(F\) such that the empirical average,

\[
L(F) = \frac{1}{n} \sum_{i=1}^{n} C(y_i F(x_i))
\]

and \(C(x)\) is a cost function.
is minimized for some suitable cost function $C(z) : \mathbb{R} \rightarrow \mathbb{R}$. The interpretation of AdaBoost as an algorithm which performs a gradient descent optimization of the sample risk has been examined by several authors, e.g., [5], [11], [15].

Mason et al. [11] proposed MarginBoost which gives a general framework of AdaBoost in terms of the margin. AdaBoost can be seen as a special case of MarginBoost with $C(z^t_i) = \exp(-z^t_i)$, where $z^t_i$ denotes the margin, $z^t_i = y_i F_t(x_i)$. In the next box, the normalized version of MarginBoost, MarginBoost.$L_1$ is summarized, in which $\beta_i$ are normalized such that they sum to one.

### MarginBoost.$L_1$ (Mason et al., [11])

1. Specify a suitable (monotonically decreasing) cost function $C(z)$.
2. Initialize $w_0(i) = 1/n$ for $i = 1, 2, \ldots, n$, and $F_0(x) = 0$.
3. For $t = 1, 2, \ldots, T$, do:
   (a) Fit a classifier $f_t(x)$ to the training data weighted by $w_{t-1}(i)$ for $i = 1, 2, \ldots, n$.
   (b) If $\sum_{i=1}^n w_{t-1}(i) y_i f_t(x_i) \geq 0$, then return $F_t(x)$, and stop.
   end If.
   (c) Choose $\beta_t$ appropriately.
   (d) Let $F_t(x) = F_{t-1}(x) + \beta_t f_t(x)$.
   (e) Set $w_t(i) = \frac{C'(z^t_i)}{\sum_{j=1}^n C'(z^t_j)}$ for $i = 1, 2, \ldots, n$.
   end For
4. Output $\text{sign}(F_T(x))$.

In the box, $C'(z)$ denotes the derivative of the cost function with respect to the margin $z$. Note that $C'(z)$ is non-positive since the margin cost function is monotonically decreasing and the normalized weight $w_t(i) = \frac{C'(z^t_i)}{\sum_{j=1}^n C'(z^t_j)} > 0$ can be interpreted as a probability, but it actually gives a gradient information, which will serve as a basis for deriving a gradient-type search algorithm in the subsequent development. If $\sum_{i=1}^n w_{t-1}(i) y_i f_t(x_i) \geq 0$, i.e., when the total sum of the weighted margins indicates correct classification over the training data, then the algorithm returns $F_t(x)$ and terminates. The readers are referred to [11] for details of MarginBoost.$L_1$.

### 3. Misclassification Loss Function and Stochastic Noise Reaction

#### 3.1. Misclassification (zero-one) loss function

Friedman et al. [6] have demonstrated that the AdaBoost algorithm decreases an exponential loss function. Figure 1 illustrates various loss functions as a function of the margin value, $z = y F(x)$, including the exponential loss function. When all the class labels are not mislabeled and hence data is noiseless, the result of correct classification always yields a positive margin since $y$ and $F(x)$ both share the same sign while incorrect one yields negative margin. The loss function for Support Vector Machine is also shown in Figure 1, which is a statistical learning method to train kernel-based machines with optimal margins by mapping training data in a higher dimension.

Shown also in Figure 1 is the misclassification loss (zero-one loss function), $I(z < 0) = I(y F(x) < 0)$, where $I(y F(x) < 0)$ denotes the indicator function with respect to the occurrence of the incorrect events, i.e., $y F(x) < 0$, which gives unit penalty for negative
Figure 1: Loss functions for two-category classification (Following [8])

margin values, with no penalty for positive ones (i.e., correct decisions). In this way, the
decision rule becomes a judgment on a zero-one loss function, which will be investigated in
this study. It is important to note that the zero-one loss function yields the Bayes minimum
classification error for binary classification [2]. In order to approximate the misclassification
loss, Sano et al. [15] proposed the sigmoidal loss function (i.e., smoothed zero-one loss
function, \( C(z) = 1/(1 + \exp(\lambda z)) \), where \( \lambda \) denotes the positive slope parameter), since the
misclassification loss is a discontinuous step function. In this study, however, the derivative
of the misclassification loss is stochastically approximated without using the sigmoidal loss
function.

The exponential loss function exponentially penalizes negative margin observations or
incorrect decisions. At any point in the training process, the exponential criterion concen-
trates much more influence on observations with large negative margins. This is considered
as one of the reasons why AdaBoost is not robust for noisy situation where there is misspeci-
fication of the class labels in the training data. Since the zero-one loss function concentrates
and uniquely influences on negative margin, it is far more robust in noisy setting where the
Bayes error rate is not close to zero, which is especially the case in mislabeled situation.

Mean-squared approximation errors are well-understood and used as a loss function in
statistics area. Unlike the zero-one loss function which considers only the misclassified
observations, the minimum squared error (MSE) criterion takes into account the entire
training samples with wide range of margin values. Hence, if MSE is adopted, the correct
classification but with \( yF(x) > 1 \) incurs increasing loss for larger values of \(|F(x)|\). This
makes the squared-error a poor approximation compared to the zero-one loss function and
not desirable since the classification results that are excessively correct are also penalized
as much as worst (extremely incorrect) cases. Other functions in Figure 1 can be viewed as
monotone continuous approximations to the misclassification loss.

Here we would like to propose the zero-one loss function which takes account of limited
influences from larger negative margins in a proper manner and, accordingly, robust against mislabeled noisy training data. Actual misclassification loss is not differentiable at $yF(x) = 0$, and one needs to use sub-gradients in general. However, in this study, we try to avoid formulating sub-gradients, and we use Stochastic Noise Reaction (SNR) technique proposed in [9] in order to evaluate the derivative of the zero-one loss function.

### 3.2. Stochastic noise reaction

Optimization problems that seek for minimization (or equivalently maximization) of an objective function have practical importance in various areas. Once a task is modeled as an optimization problem, general optimization techniques become applicable; e.g., linear programming, gradient methods, etc. One may encounter difficulties, however, in applying these techniques when the objective function is non-differentiable or when it is defined as a procedure. To deal with such a case, Koda and Okano [9] proposed a function minimization algorithm, called Stochastic Noise Reaction (SNR) that updates solutions based on approximated derivative information. They apply SNR algorithm to traveling salesman problem (TSP), a representative combinatorial optimization problem, and show its effectiveness [12]. We illustrate here only an essence of SNR needed in the present boosting study.

Consider an objective function $L(z) : \mathbb{R}^n \to \mathbb{R}$, then the gradient vector of $L(z)$ is defined by

$$
\nabla L(z) = \left( \frac{\partial L(z)}{\partial z_1}, \frac{\partial L(z)}{\partial z_2}, \ldots, \frac{\partial L(z)}{\partial z_n} \right)^T.
$$

(3)

To avoid the exact gradient calculation of Equation (3), SNR technique injects a Gaussian white noise, $\xi_i \in N(0, \sigma_i^2)$, into a variable $z_i$ as

$$
z_i(j) = z_i + \xi_i(j),
$$

(4)

where $\xi_i(j)$ denotes the $j$-th realization of the noise injected into the $i$-th variable. Each component of a derivative is approximated for sufficiently small $\sigma_i < \sqrt{2}$, without explicitly differentiating the objective function by using the relation,

$$
\frac{\partial L(z)}{\partial z_i} \approx \frac{1}{\sigma_i^2} \frac{1}{M} \sum_{j=1}^{M} L(z(j))\xi_i(j) = d(z_i),
$$

(5)

where $M$ is a loop count for taking the average. For details of the derivation of Equation (5), the readers are referred to [12]. A concise derivation of Equation (5) is given in Appendix. It is expected that Equation (5) yields a good approximation when $\sigma_i \to 0$ (cf. Equation (A3) in Appendix). The value of $M$ is set to 100 in all of the numerical experiments in Section 5. In actual implementations, all the realizations of the noise should be generated and normalized in advance to ensure sample mean $\frac{1}{M} \sum_{j=1}^{M} \xi_i(j) = 0$ and sample variance $\frac{1}{M} \left( \xi_i(j) - \frac{1}{M} \sum_{j=1}^{M} \xi_i(j) \right)^2 = \sigma_i^2$.

### 3.3. SNR application to zero-one loss function

Based on Equation (5) with $\sigma_i = 1$, the approximated derivative for the misclassification loss, i.e., zero-one loss function,

$$
I(z < 0) = \begin{cases} 
1 & \text{if } z < 0 \\
0 & \text{otherwise}
\end{cases}
$$

(6)

is shown in Figure 2. Figure 2 depicts that the discontinuous point of the zero-one loss function at $z = 0$ is leveled, and the derivative is obtained. Note that the stochastic
gradient resembles the derivative of $C(z) = \frac{1}{2}(1 - \tanh(z))$, which is the smoothed zero-one loss function and is differentiable as $C'(z) = \frac{1}{2}(\tanh(z) + 1)(\tanh(z) - 1)$. It is recognized that the stochastic gradient is negative and smallest at the origin, and equals to 0 as $z$ is distant from the origin. It is difficult to observe, however, that there could be a positive derivative at distant points from the origin.

![Figure 2: Derivative approximation for zero-one loss function](image)

### 4. Proposed Boosting Method–SNRBoost

Based on the algorithmic framework of MarginBoost$L_1$ and Stochastic Noise Reaction (SNR), the proposed boosting method referred to as SNRBoost is presented in this section. Essentially the proposed algorithm works as in MarginBoost$L_1$, however, in deriving the method, we use the zero-one loss function (cf. Equation (6)) as the margin cost function in finding pattern weightings for the training set.

In principle, any boosting algorithm selects iteratively a base learner or hypothesis at a time and then updates the weight $w$. In MarginBoost$L_1$, one updates only the weight of the last classifier selected as described in the line 3(e) of MarginBoost$L_1$ algorithm as follows:

$$w_t(i) = \frac{C'(z^i_t)}{\sum_{j=1}^{t} C'(z^j_t)},$$

where $z^i_t$ denotes the margin of the $i$-th training data at the $t$-th iteration, $z^i_t = y_iF_t(x_i)$, and $C(z^i_t)$ is the differentiable (monotonically decreasing) cost function. Recall that $C'(z^i_t) < 0$ and the normalized weight $w_t(i) > 0$ can be interpreted as a probability, but it actually gives a gradient information.

Let $d_t(i)$ denote the stochastic gradient approximated by using SNR algorithm (cf. Equation (5)) for the zero-one loss function at $z^i_t$. Then, we may incorporate SNR algorithm in updating the weight by replacing the derivatives $C'(z^j_t)$ involved in Equation (7), uti-
lizing a formal relationship $C'(z^t_j) = d_t(j)$ even when the margin cost function $C(z)$ is non-differentiable, zero-one step function, i.e., $C(z) = I(z < 0)$.

Therefore, in view of our ultimate goal to achieve a gradient-type minimization through the zero-one loss function, we propose to update the pattern weighting as follows:

$$w_t(i) = \frac{d_t(i)}{\sum_{j=1}^{n} d_t(j)}. \quad (8)$$

Note, however, Equation (8) may result in computing negative weights due to a stochastic nature of SNR algorithm and $w_t(i) \geq 0$ is not automatically satisfied. Hence, if $w_t(i) < 0$, then it is set to 0 and the computing process is continued to obtain weightings of the training set for a selection of the next classifier which minimizes the weighted training error. If the total sum of the weighted margins becomes non-negative meaning correct classification over the training data (i.e., $\sum_{i=1}^{n} w_{t-1}(i)y_if_t(x_i) \geq 0$), then the algorithm returns $F_t(x)$ and terminates.

Above weighting rule implies that the weight is assigned proportional to the normalized value of the corresponding gradient computed from Equations (7) or (8). For instance, the largest weight is given to the training data with largest gradient component (related to the quantity often called the edge in supervised learning [1]); this is easily understood as the training data with greatest importance is the one that makes most progress in the gradient-type search. Hence, MarginBoost. $L_1$ and SNRBoost both fall into the category of gradient-type boosting algorithms.

For the appropriate choice of $\beta_t$ in Equation (1), which also appears in the lines 3(c) and 3(d) of MarginBoost-$L_1$ algorithm, we propose $\beta_t = K/(K + t)$, where $K$ is a suitable integer. This setting of $\beta_t$ is based on the well-known stochastic approximation technique [2], which satisfies the conditions

$$\lim_{T \to \infty} \sum_{t=1}^{T} \beta_t = \infty, \quad \text{and} \quad \lim_{T \to \infty} \sum_{t=1}^{T} \beta_t^2 < \infty. \quad (9)$$

Note, if the technique is used in the gradient-type search, the proposed method guarantees a convergence of $F_t$ to its local optimal point. In our numerical experiments in Section 5, the proposed method of setting $\beta_t$ with $K = T$ is used in the implementation of MarginBoost-$L_1$ and SNRBoost.

We have now discussed all the necessary parts of the proposed algorithm, which is summarized in the following box as pseudo-code.

5. Numerical Experiments

In this section, numerical results are presented and, especially, the robustness of the proposed method are analyzed and compared with that of AdaBoost and MarginBoost-$L_1$ with $C(z) = \frac{1}{2}(1 - \tanh(\lambda z))$, where $\lambda$ is the positive slope parameter. Compared with test error rates of MarginBoost-$L_1$, the validity of approximation of zero-one function by SNR is also confirmed. It is expected that the test error rates of the proposed method when $\sigma^2$ approaches 0 have same behavior of MarginBoost-$L_1$ when $\lambda$ becomes large. The normalized version of AdaBoost and MarginBoost-$L_1$ such that $\sum_{s=1}^{t} \beta_s = 1$ is used to compare effects of the loss function. We focus our attention to classification results for mislabeled (i.e., noisy) cases. The back-propagation neural network with single hidden layer is used as a base learner for all the three boosting methods. The number of units in hidden layer
SNRBoost

1. Initialize $w_0(i) = 1/n$ for $i = 1, 2, \ldots, n$, $F_0(x) = 0$ and specify $K$.
2. For $t = 1, 2, \ldots, T$, do:
   (a) Fit a classifier $f_t(x)$ to the training data weighted by $w_{t-1}(i)$ for $i = 1, 2, \ldots, n$.
   (b) If $\sum_{i=1}^{n} w_{t-1}(i)y_if_t(x_i) \geq 0$, then return $F_t(x)$, and stop.
   (c) Set $\beta_t = K/(K + t)$.
   (d) Let $F_t(x) = F_{t-1}(x) + \beta_tf_t(x)$.
   (e) Compute approximated derivatives for zero-one loss function $d_t(i)$ using SNR for $i = 1, 2, \ldots, n$.
   (f) Set $w_t(i) = \frac{d_t(i)}{\sum_{j=1}^{n} d_t(j)}$ for $i = 1, 2, \ldots, n$.
   (g) If $w_t(i) < 0$ then $w_t(i) = 0$.
end For
3. Output $\text{sign}(F_T(x))$.

(i.e., hidden units) is 3. Since a multilayer neural network has been shown to be able to define an arbitrary decision function, with a flexible architecture in terms of the number of hidden units, it thus provides the ideal potential for generalization of training results by boosting. Throughout the experiments, SNR algorithm uses an estimator of the gradients which averages 100 noisy samples, i.e., $M = 100$ (cf. Equation (5)).

5.1. Toy example

For numerical experiments, toy data (with 2% mislabeled case) is generated as follows:
1. Generate uniformly $x = (x_1, x_2) \in \chi = [-4, 4] \times [-4, 4]$;
2. assign $y = \text{sign}(F(x))$, where $F(x) = x_2 - 3\sin(x_1)$;
3. sort $|F(x_i)|$ by descending order;
4. sample randomly 2% from top 50% (far case) or bottom 50% (near case) examples;
5. flip sampled examples in Step 4.

In Step 2, note that $F(x) = x_2 - 3\sin(x_1)$ is used as a nonlinear decision function. In Step 4, we generate two mislabeled cases; one where mislabeled data are located far from the decision boundary (far case) and the other where mislabeled data are concentrated near the decision boundary (near case). Figure 3(a) shows the far case, while Figure 3(b) shows the near case, and Figure 3(c) shows the noiseless case. The decision boundary is given by the solid line.

The number of training data is 300 and that of test data is 1000. In all the experiments, noiseless data is used as test data. Iteration number of the base learner, which is referred to as round (number), is set to 1000, and the stopping condition is not used to compare effects of the margin cost function utilized. Above procedure is repeated 5 times, each time different dataset is generated and the performance of boosting methods for each dataset is evaluated. Figure 4 shows the average performance of test error rates. Variance of the proposed SNR method is set to $\sigma^2 = 1.0$, and for MarginBoost.$L_1$, $\lambda$ is set to $\lambda = 1.0$. In Figure 4(a)(far case), AdaBoost, MarginBoost.$L_1$ and SNRBoost fall into 0.038%, 0.030% and 0.030% respectively, and in Figure 4(b)(near case) 0.037%, 0.026% and 0.028% at 1000 round (boosting iteration). In Figure 4(c)(noiseless case), three methods fall into 0.021%, 0.027% and 0.027% respectively. In all three cases, the performance of SNRBoost exhibits
Figure 3: Toy Example: (a) Case of 2% mislabeled data located far from the decision boundary; (b) Case of 2% mislabeled data concentrated near the decision boundary; (c) Noiseless data
similar performance to MarginBoost.$L_1$ with $C(z) = \frac{1}{2}(1 - \tanh(z))$. It is clear that the performance of SNRBoost is superior to AdaBoost in mislabeled cases (see Figures 4(a) and 4(b)).

5.2. Higher-dimensional example

In this experiment, the level of variance of the proposed SNR method is changed as $\sigma_i^2 = 1.0, 0.1, 0.01$, and MarginBoost.$L_1$ is executed using the range of slope parameters with $\lambda = 1, 5, 10$. We focus our attention to classification results for the mislabeled (i.e., noisy) case near decision boundary, the mislabeled case far from decision boundary, and the correctly labeled (i.e., noiseless) case, as in toy data experiments.

5.2.1. Generation of mislabeled data

For numerical experiments, data (with 2% mislabeled case) is generated as follows:
1. Decide $n$, the size of training and test examples;
2. generate $n$ training and $n$ test examples from five-dimensional standard normal distribution $x \sim N^5(0, I)$;
3. decide $r^2$, the squared-radius from the origin, for all examples;
   \[ r(x_i)^2 = \sum_{j=1}^{5} x_{ij}^2 \ (i = 1, \ldots, 2n) \]
4. decide threshold $th$ by the median of $r(x)^2$;
5. assign $y = \text{sign}(F(x))$, where $F(x) = r(x)^2 - th$;
6. sort $|r(x_i)^2 - th|$ $(i = 1, \ldots, n)$ corresponding to training examples by descending order;
7. sample randomly 2% from top (or bottom) 50% of the outcome of Step 6;
8. flip the label of sampled examples in Step 7.

In Step 5, note that $F(x) = r(x)^2 - th$ is used as a nonlinear decision function. In the mislabeled case far from decision boundary, samples from top 50% training example are selected in Step 7. In the mislabeled case near decision boundary, samples from bottom 50% training examples are chosen as training examples. It is noted that the mislabeled data is only contained in training examples $x_i \ (i = 1, \ldots, n)$, and the test examples $x_i \ (i = n+1, \ldots, 2n)$ are noiseless. Above procedure is repeated 5 times, each time different dataset is generated and the performance of boosting methods for each dataset is evaluated. The number of training and test data is 1000 each. Iteration number of the base learner is 1000, and the stopping condition is not used to compare effects of the margin cost function.

5.2.2. Numerical results

We plot in Figure 5 the test error curves for 2% mislabeled data located far from the decision boundary, and in Figure 6 that for 2% mislabeled data near the decision boundary. In Figure 7, the test error curves are shown for noiseless case. In each figure, (a) shows AdaBoost test error rates, (b) test error rates of the proposed method, with $\sigma_i^2 = 1.0, 0.1, 0.01$, (c) test error rates of the MarginBoost.$L_1$ with $\lambda = 1, 5, 10$, and (d) comparison of test error rates of AdaBoost, SNRBoost and MarginBoost.$L_1$, respectively.

(i) Mislabeled case far from decision boundary

In Figure 5(a), AdaBoost test error rate falls into 0.105% at 1000 round (boosting iteration). In Figure 5(b), for SNRBoost with $\sigma_i^2 = 0.01$, test error rate falls into 0.048% at 1000 round. In Figure 5(c), for MarginBoost.$L_1$ with $\lambda = 10$, test error rate falls into 0.048% at 1000 round. In Figure 5(d), on test error rates, the performance of SNRBoost with $\sigma_i^2 = 0.01$ is superior to that of AdaBoost and exhibits similar performance to MarginBoost.$L_1$ with $\lambda = 10$. 

Figure 4: Comparison of three boosting methods for toy example: (a) Test error rates of three boosting methods in 2% mislabeled data located far from the decision boundary; (b) Test error rates of three boosting methods in 2% mislabeled data concentrated near the decision boundary; (c) Test error rates of three boosting methods in noiseless data
Figure 5: Comparison of three boosting methods for 2% mislabeled data far from decision boundary: (a) Test error rates of AdaBoost; (b) Test error rates of SNRBoost; (c) Test error rates of MarginBoost \( L_1 \); (d) Test error rates of three boosting methods

(ii) Mislabeled case near decision boundary
In Figure 6(a), AdaBoost test error rate falls into 0.070% at 1000 round. In Figure 6(b), for SNRBoost with \( \sigma_i^2 = 0.01 \), test error rate falls into 0.049% at 1000 round. In Figure 6(c), for MarginBoost \( L_1 \) with \( \lambda = 10 \), test error rate falls into 0.053% at 1000 round. In Figure 6(d), on test error rates, the performance of SNRBoost with \( \sigma_i^2 = 0.01 \) is superior to that of AdaBoost and exhibits slightly better performance than that of MarginBoost \( L_1 \) with \( \lambda = 10 \).

(iii) Noiseless case
In Figure 7(a), AdaBoost test error rate falls into 0.048% at 1000 round. In Figure 7(b), for SNRBoost with \( \sigma_i^2 = 0.01 \), test error rate falls into 0.038% at 1000 round. In Figure 7(c), for MarginBoost \( L_1 \) with \( \lambda = 10 \), test error rate falls into 0.044% at 1000 round. In Figure 7(d), the performance of SNRBoost with \( \sigma_i^2 = 0.01 \) is superior to that of AdaBoost and exhibits better performance than that of MarginBoost \( L_1 \) with \( \lambda = 10 \).

From the above, it is found that the performance of the proposed SNRBoost is improved when \( \sigma_i^2 \) is smaller, while that of MarginBoost \( L_1 \) with \( C(z) = \frac{1}{2}(1 - \tanh(\lambda z)) \) is improved as \( \lambda \) becomes larger. We note that the proposed margin cost function for MarginBoost \( L_1 \)
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Figure 6: Comparison of three boosting methods for 2% mislabeled data near decision boundary: (a) Test error rates of AdaBoost; (b) Test error rates of SNRBoost; (c) Test error rates of MarginBoost\(L_1\); (d) Test error rates of three Boosting Methods

approaches the zero-one step function as \(\lambda\) becomes larger, which may validate the use of the zero-one loss function in the present method. As expected, SNR method gives improved accuracy when \(\sigma_i^2\) is smaller (cf. Equation (A3) in Appendix). In summary, SNRBoost exhibits a higher potential for generalization than AdaBoost.

6. Conclusion

We developed a new, robust boosting method against mislabeled, noisy data. The new formulation uses the misclassification loss function, i.e., zero-one step function. In deriving the algorithm, Stochastic Noise Reaction technique [9] is used to approximate the gradient of the zero-one loss function. Performance evolution (i.e., error minimization) of the proposed method is compared with that of AdaBoost and MarginBoost\(L_1\) with \(C(z) = \frac{1}{2}(1 - \tanh(\lambda z))\) through intensive numerical experiments. As a result, the robustness of the proposed method compared to AdaBoost in the mislabeled cases is validated. As another contribution, the proposed methods developed the boosting method for non-differentiable loss function using stochastic gradient approximation.
Figure 7: Comparison of three boosting methods for noiseless data: (a) Test error rates of AdaBoost; (b) Test error rates of SNRBoost; (c) Test error rates of MarginBoost.\( L_1 \); (d) Test error rates of three Boosting Methods

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Appendix. Derivation of Equation (5)

The Stochastic Noise Reaction (SNR) algorithm, Equation (5), uses the following relationship:

\[
\frac{\partial L(z)}{\partial z_i} \approx \frac{1}{\sigma_i} \langle L(z + \xi) \xi_i \rangle, \tag{A1}
\]

where \( L(z) : \mathbb{R}^n \rightarrow \mathbb{R} \) is a continuously differentiable function, and \( \langle \cdot \rangle \) denotes the expectation operator. In Equation (A1), \( \xi \) is an \( n \)-dimensional vector each of whose components \( \xi_i \) is an independent Gaussian noise with mean 0 and standard deviation \( \sigma_i \); i.e.,

\[
\langle \xi_i \xi_j \rangle = \sigma_i^2 \delta_{ij}, \quad \langle \xi_i^{2r+1} \rangle = 0, \quad \langle \xi_i^{2r} \rangle = \sigma_i^{2r} \frac{(2r)!}{2^{r} r!}, \tag{A2}
\]
where $\delta_{ij}$ denotes the Kronecker delta, and $r$ is a non-negative integer value.

Using (A2) in a Taylor series expansion of $L(z + \xi)$ around $z$ gives

$$\frac{1}{\sigma_i^2} \langle L(z + \xi) \rangle = \frac{1}{\sigma_i^2} \langle \{ L(z) + \sum_{k=1}^{\infty} \frac{1}{k!} \sum_{j=1}^{n} (\xi_j \frac{\partial}{\partial z_j})^k L(z) \} \xi_i \rangle$$

$$= \frac{1}{\sigma_i^2} \{ L(z) \langle \xi_i \rangle + \sum_{j=1}^{n} (\xi_j \frac{\partial}{\partial z_j}) L(z) \}$$

$$= \frac{1}{\sigma_i^2} \sum_{k=1}^{\infty} \frac{1}{k!} (\xi_i) \frac{\partial^{k-1}}{\partial z_i^{k-1}} L(z)$$

$$= \frac{\sigma_i^2}{\sigma_i^2} \frac{\partial L(z)}{\partial z_i} + \sum_{k=4,6,8,...} \frac{1}{(k-1)!} (\xi_i) \frac{\partial^{k-1}}{\partial z_i^{k-1}} L(z)$$

$$= \frac{\partial L(z)}{\partial z_i} + \sum_{r=2}^{\infty} \frac{1}{(r-1)!} \left( \sigma_i \right)^{2(r-1)} \frac{\partial^{2r-1}}{\partial z_i^{2r-1}} L(z)$$

(A3)

for sufficiently small $\sigma_i < \sqrt{2}$. It is expected that Equation (A3) yields a good approximation when $\sigma_i \to 0$. In Equation (A3), it is important to note that the differential operator has disappeared and the gradient information is given as an expected value of the product of the cost function $L(z + \xi)$ and the noise $\xi_i$. Since the present method will smoothen the margin cost function to be estimated by sampling and averaging, it may be efficiently applied to discontinuous functions, such as piecewise constant functions or zero-one loss function. In Equation (5), the expectation is replaced by the sample mean.

References


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